

SUMMARY DYNAMICS MODULE N8

SUBJECT

EQUATION

DISCUSSION

Rigid Body  
Motion

$$\sum \bar{F} = m\bar{a}$$

$$\sum \bar{M}_a = \frac{d\bar{H}_G}{dt}$$

Motion of a rigid body  
due to forces applied

to it may be expressed  
by  $ma$  at the CG and a  
moment  $H_G$  about CG.

Angular

$$\bar{H}_G = I_G \bar{\omega}$$

$$\frac{d\bar{H}_G}{dt} = I_G \alpha$$

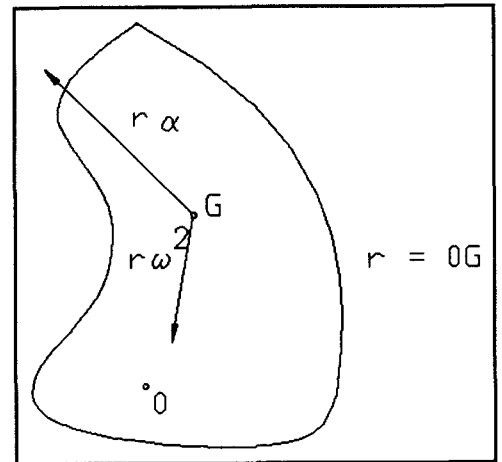
$I_G$  - moment of inertia  
about CG.

Non-Centroidal  
Rotation

$$a_{t_G} = r \alpha$$

$$a_{n_G} = r \omega^2$$

$$\sum M_0 = I_0 \alpha$$



### WORDS TO KNOW MAJOR MODULE 8

1. Center of Gravity - that point in a body at which its weight may be taken to act and about which the body could be balanced, though placed in any position.
2. Center of Mass - that point in a body where any imaginary plane or real (if possible) could pass through the body and divide it into two equal parts of equal mass. The Center of Mass is also where the resultant force acts due to the body's inertia, when it is accelerated.
3. Inertia - that property of a body which tends to resist a change in the body's motion, whether the body is at rest or already in motion.